Performance Enhancement Functionality in MARS[®] version 2024.0

Please Read -- Important information on single-thread vs multi-thread processing in MARS®

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MARS Technical Support information

To get the most out of the MARS[®]software's multi-threading capabilities, please follow these general guidelines regarding the location of the data being processed. Note that testing may be necessary to achieve the best results for each particular case.

- Network disk server
 - o High speed Input/Output (I/O) always use the maximum number of threads available
 - Medium to lower speed I/O (or unknown) single thread (1) is recommended
- Internal drive
 - SSD (solid state drive)
 - High end level (NVMe) always use the maximum number of threads
 - Consumer level using multiple threads should perform better than single thread but experimenting on what maximum thread count to use for each process is recommended
 - HDD (hard disk [spinning] drive)
 - High RPM speed (e.g., 10,000 or 15,000) lower multi-thread count is recommended and testing is encouraged
 - Lower RPM speed (e.g., 5400 or 7200) single thread is recommended
- External drive
 - USB 3.x
 - With a spinning drive (typical of most external drives) single thread is recommended
 - With an SSD using multiple threads should perform better than single thread but experimenting on what maximum thread count to use for each process is encouraged
 - o USB 2.0 single thread is strongly recommended

Note - Using temporary local disk space in the scenario where the input or output data is located on a slower disk I/O location typically speeds up throughput if the local temp space drive is a high-speed disk such as an SSD.

1. Keyboard Accelerators:

Most functions in MARS[®] support keyboard shortcuts (hot keys) which speed manipulation and use of the application.

Keyboard Accelerator for the Help File:

F1 Opens the Help Topics document for MARS[®]

Common Keyboard Accelerators:

Ctrl-N	New MARS [®] project (.mpd file).					
Ctrl-O	Open MARS [®] project (.mpd file). Does not open any other type of file.					
Ctrl-S	Save MARS [®] project (.mpd file).					
Q	Activate 'Pan' tool.					
+	Zoom in by a fixed amount (25%). Use '+' on the regular keys (no 'Shift' needed) or number pad.					
_	Zoom out by a fixed amount (25%). Use '-' on the regular keys or number pad.					
Esc	Exit out of any open dialog box.					
L	Toggle 'Lock to view 100%' tool on/off.					
Т	Toggle between viewing LiDAR points and viewing a TIN surface.					
Х	Toggle on/off LiDAR points.					
0	Toggle on/off orthophotography (imagery).					
С	Toggle on/off contour lines.					
S	Toggle on/off shapefiles.					
М	Toggle 'Measure' tool on/off.					
I	Toggle 'Inspect' tool on/off.					
Ctrl-A	Allow display of all LiDAR point classifications.					
Ctrl-K	Allow display of only the model key-points (Class 2 with MKP bit flag set to 'On').					
Ctrl-G	Allow display of only the ground point classification (2).					
Ctrl-E	Color points or TIN by elevation.					
Ctrl-I	Color points or TIN by intensity.					
Ctrl-C	Color points or TIN by classification.					
Ctrl-R	Color points or TIN by return.					
Ctrl-L	Color points or TIN by collection scan.					
Ctrl-J	Color points or TIN by RGB values.					
Ctrl-F	Color points or TIN by imagery RGB values (Color by Imagery Fusion).					
Ctrl-D	Copy the X, Y (and Z, if available) coordinates values shown at the right side of the Status Bar to the Windows clipboard, based on the current cursor location.					
Ctrl-T	Toggle Fast TIN on/off.					
Ctrl-Z	Undo last vertex drawn or point placed when drawing 2D features from the 'Vector Creation' tab. Also undo last vertex drawn when creating a polygon with the 'Filter Digitized Polygon' tool.					
Z	Open the 'Elevation Repeat Colors Options' interface.					

Keyboard Accelerators for Cross-Section/Profile View Manipulation (these options are only available when the cross-section/profiling window is open and selected)

W	Activate 'Place Adjustable Cross-Section Line' tool.			
D	Set Depth of the cross-section/profile area.			
Up Arrow (1)	t) Move the cross-section/profile area forward.			
Down Arrow (♣)	Move the cross-section/profile area backward.			
Right Arrow (➡)	Rotate the cross-section/profile area clockwise.			
Left Arrow (年)	Rotate the cross-section/profile area counter-clockwise.			
Underscore (_) In the Cross-Section/Profile window, toggle between 'Cross-Section' and 'Profile by Collection Scan' views.				
Ctrl-A	Allow display of all LiDAR point classifications.			
Ctrl-K	Allow display of only the model key-points (Class 2 with MKP bit flag set to 'On').			
Ctrl-G	Allow display of only the ground point classification (2).			
Ctrl-E	Color points or TIN by elevation.			
Ctrl-I	Color points or TIN by intensity.			
Ctrl-C	Color points or TIN by classification.			
Ctrl-R	Color points or TIN by return.			
Ctrl-L	Color points or TIN by collection scan.			
R Activate the 'Rotate Profile' window and allow the user to rotate the cross-section, a specified number of degrees.				

Keyboard Accelerators for Point Editing in the LAS Map View Window

0-9	Addify the currently selected points to the new classification indicated by the number key pressed. For example, the '5' key modifies selected points to the point classification 'High Vegetation'.					
G	Activate the 'Edit Place Polygon' tool, which selects all points within the boundary of the user's manually defined polygon.					
Space	Modify the currently selected points to the last target classification used. For example, if the last classification edited had a value of 6, then pressing the space bar will modify the <i>currently</i> selected points to the same target classification, 6.					
U	Unselect all currently selected points.					
Ctrl-H	Allow display of only classification (8).					
Ctrl-M	Allow display of only the ground points classification (2) and the superseded classification (20).					
Ctrl-P	Activate the small paintbrush tool for selecting points.					
Р	Activate the medium paintbrush tool for selecting points.					
Shift-P	Activate the large paintbrush tool for selecting points.					
E	Activate 'Filter Region' tool.					
Ν	Re-use the last polygon created with the 'Filter Digitized Polygon' tool					
Esc	Leave the current editing mode.					
Ctrl-Z	Undo the last edit step.					
Ctrl-Y	Redo an edit step.					
Z	Open the 'Elevation Repeat Colors Options' interface.					

Ctrl-	Pan up by pre-selected percentage.			
Ctrl-↓	Pan down by pre-selected percentage.			
Ctrl-←	Pan left by pre-selected percentage.			
Ctrl-→	Pan right by pre-selected percentage.			

Keyboard Accelerators for Point Editing in the Cross-Section/Profile Window

0-9	Modify the currently selected points to the new classification indicated by the number key pressed. For example, the '5' key modifies selected points to the point classification 'High Vegetation'.					
Space	Modify the currently selected points to the last target classification used. For example, if the last classification edited had a value of 6, then pressing the space bar will modify the <i>currently</i> selected points to the same target classification, 6.					
U	Unselect all the currently selected points.					
/	Activate the 'Edit Scrape Above' tool.					
?	Activate the 'Edit Scrape Below' tool.					
S	Activate the 'Line String Above' tool, which selects all points above a manually defined line string.					
Shift-S	Activate the 'Line String Below' tool, which selects all points below a manually defined line string.					
Ctrl-P	Activate the small paintbrush tool for selecting points.					
Р	Activate the medium paintbrush tool for selecting points.					
Shift-P	Activate the large paintbrush tool for selecting points.					
E	Activate 'Filter Region' tool.					
Esc	Leave the current editing mode.					
Ctrl-Z	Undo the last edit step.					
Ctrl-Y	Redo an edit step.					
D	Open the 'Set Cut Depth' window to adjust the cut area depth of the cross-section/profile tool.					
Z	Open the 'Elevation Repeat Colors Options' interface.					
R	Activate the 'Rotate Profile' window and allow the user to rotate the cross-section/profiling area a specified number of degrees.					

Keyboard Accelerators for Breakline Editing in the LAS Map View Window

Esc	Leave the current editing mode or dialog window.					
Shift-Mouse Click	Holding down the shift key while compiling breaklines will cause the breakline to snap to the user- designated point. The point to which the breakline will be snapped will be determined by the feature drop-down code list. Choose either: 'startendvertex', 'vertex', 'nearestpoint', or 'midpoint'.					
Ctrl-Mouse Click	Ctrl-Click on a breakline the first time will collect that breakline's Z-value, and Ctrl-Click a second time will transfer that collected Z-value to a new breakline point that is currently being compiled.					
A	When pressed and released during breakline collection, begins the creation of an arc (splined curve) in the breakline. The next two left-clicks will be the center and endpoint of the arc, respectively.					
В	Toggle on/off the auto-pan mode.					
V	Toggle on/off auto-pan edge markers.					
Alt	Holding the 'Alt' key down while in collection mode will allow the user to pan across the data when auto-pan is turned off. The cursor will temporarily turn from collection tool to pan tool while the 'Alt' key is pressed.					
Ctrl-B	Toggle display of breaklines on/off.					

Ctrl-M	Allow display of only the ground points classification (2) and the superseded classification (20).				
Ctrl-T	Toggle Fast TIN on/off.				
Ctrl-Z	Undo last vertex drawn when placing a breakline.				
Shift-B	Quick save of breaklines without confirmation (when path/name has previously been established).				

Keyboard Accelerators for Editing Point Classes

To enter a number for any class (0-9, 10-99, or 100-255), go to the '**Options Tab**' and click the '**Miscellaneous**' button. In the upper-right corner of this window is the 'Editing Options' section. Check the box labeled '**Enable two or three digit class keyboard input'**. If LiDAR data contains classes with 2 or 3 digits (e.g., Class 14 or Class 122), this option can be useful during editing. Simply enter the 2- or 3-digit class, choose 'Enter' on the keyboard, and any LiDAR points highlighted will be changed to that classification. Single-digit class values can also be applied while the 'Enable two or three digit class keyboard input' option is checked by choosing 'Enter' on the keyboard after the single number is entered. The points will then be reclassified. When the 'Enable two or three digit class keyboard input' option is unchecked, points selected cannot be reclassified to 2- or 3-digit classes because as soon as one number is entered (interpreted by MARS[®] as a 1-digit class) the points are automatically reclassified *without* hitting the 'Enter' key. For example, the user can select LiDAR points needing to be reclassified and enter '15' if that is the intended target class. Without the 'Enable two or three digit class keyboard input' option checked, the points selected will be reclassified to Class 1 because this was the first number entered on the keyboard to reclassify data. See the upper-right of the 'Miscellaneous Options' window below.

🗱 Miscellaneous Options	- 🗆 🗙				
Viewing	Editing Options Enable two or three digit class keyboard input				
 Double-click to zoom to tile extent Display LiDAR graphics in Overview window 	Check Point Report Options Number of significant figures 3				
Snapping Option	Panning Options				
Drawing	O 50% O 75%				
Point Size - Main View 2 pixels	New Version of MARS Program Update Checking				
Point Size - Profile 2 pixels	O Never O Daily Check for Update Now				
Cross-Section / Profile Window	Folder Dialog Option Remember last folder location				
Default cut area depth 10 (ground units)					
Forward/back percentage ○ 25% ○ 50% ● 75% ○ 90% ○ 100%					
Arrange Cross-Section/Profile window	Temp Folder				
O Horizontally	C:\Users\lidar				
Turn on location cursor X in main view					
Show toolbar in cross section window	Help OK Cancel				

2. Toggle Buttons:

The toggle buttons found on the View Tab provide easy access for control of the display. Not all toggle buttons available on the tab speed up the performance and functionality of MARS[®], so some are not described here.

The View Tab:



- E Color by Elevation: Displays LiDAR points rendered by elevation.
- **Color by Intensity:** Displays LiDAR points rendered by intensity value.
- Color by Classification: Displays LiDAR points rendered by classification.
- **Color by Return**: Displays LiDAR points rendered by return value.
- **Color by Collection Scan:** Displays LiDAR points rendered by collection scan.
- **Color by Ground Color:** Displays user-defined ground class(es) by RGB values and all other points by classification. (Must have imagery loaded for this option to become available.)
- **Color by RGB:** Temporarily fuses the color from an ortho image to the LiDAR points for display purposes.
- **E** Color by Imagery (Fusion): Drapes imagery over the LiDAR points. (Must have imagery loaded to be enabled)
- Blend with Intensity: Blends Intensity values with any other method (e.g., Elevation, Classification, Return, etc.)
- **Color by CIR:** Uses the R(ed), G(reen), B(lue), and N(ear Infrared) values stored for each LiDAR point to render the point cloud or TIN as a <u>4-band</u> pseudo-image. This option is intended for use with Point Data Record Format (PDRF) 8 point clouds that can store NIR values.
- **Color by Hillshade:** This tool colors an elevation float grid by hillshade on the fly. It is only available if one or more float grids have been loaded in MARS[®] and can be used in 3D in conjunction with a float grid (*.flt) file.
- Solor by Z Delta: This tool will color the points in the LiDAR data by the vertical difference in flight lines.
- Color by User Data: Displays LiDAR points rendered by the User Data value. There is currently no standardized use for this field.
- **Bit Flag:** This tool brings up the 'Bit Flag Display Settings' interface which allows display control of LAS v1.4 points based on several bit flag settings Synthetic, Model Key-point, Withheld, Overlap, Edge of Collection Scan, Scanner Channel, and Scan Direction.



Points: Display LiDAR data as points. Also known as a 'point cloud' display.

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TIN: Display LiDAR data as a TINned surface.

Lock to view 1%: Limits the display of point density to 1% (or less) of the loaded points when toggled on.

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3. Multi-Threading Capabilities:

Multi-Threading	
Number of threads to use	8

The multi-threading control pictured above is found in the following tools and functions. It speeds up processing by utilizing a user-specified amount of a computer's processing power. For best performance, there should be a minimum of eight (8) GB of RAM <u>available</u> (not just installed) per thread.

a. Export:

The multi-threading option is available for most export types in MARS[®]. The control will default to the maximum number of threads the computer has available for processing. Leave as is, or enter a lower number of threads to be used. If '1' is entered in the text box, it is equivalent to single-threading the process.

b. QC processes:

The multi-threading option is found in most of the MARS[®] QC functions, including the Raster QC tool and all drop-downs of the QC Module. The control will default to the maximum number of threads the computer has available for processing. Leave as is, or enter a lower number of threads to be used. If '1' is entered in the text box, it is equivalent to single-threading the process.

c. Batch Process Tiles:

For this tool, the multi-threading control will default to a value of '1' (single-threading). Enter a larger number of threads to process multiple tiles in parallel. Depending on the density of the LAS data and the tile size, some testing may be needed to find the optimal multi-thread value.

d. MARS® GeoCalc:

For this tool, the control will default to the maximum number of threads the computer has available for processing. Leave as is, or enter a lower number of threads to be used. If '1' is entered in the text box, it is equivalent to single-threading the process.

e. Add Spatial Index:

For this tool, the multi-threading control will default to a value of '1' (single-threading). Enter a larger number of threads to process multiple LAS files in parallel. Depending on the file size, some testing may be needed to find the optimal multi-thread value. Multi-threading the Spatial Indexing functions across a USB 2.0 connection is <u>not recommended</u> as the intensive file reads/writes (disk I/O) may cause hangs or slower overall performance than single-threading. USB 3.0 or later can be used but may be limited in performance depending on the speed (spin rate) of the external drive.

Several other tools and functions also contain the multi-threading option, including Convert, Populate Statistics on Tile Scheme, Collection Scan Polygon Generator, and others. In all cases, this option can shorten processing times by using the computer's resources more efficiently.

4. Double-Click on Tile in Tile Scheme:

To use this shortcut - which will speed processes such as hand editing - a tile layout shapefile must be loaded into MARS[®]. Once a tile shapefile is loaded, the user can zoom to the extents of a single tile by double-clicking inside that tile's boundary, if the 'Double-click to zoom to tile extent' box is checked in the 'Viewing' section of **Options** \rightarrow **Miscellaneous**.

5. Bookmarks:

A bookmark can be used to mark a certain place in the data and makes revisiting that same place easier and faster. By saving a bookmark, the user will be able to click on the bookmark name in the future and be taken to the place in the data that the bookmark was placed. Bookmarks are convenient when editing to be able to pick up editing in a specific location, or to save a place where rework needs to be done. The bookmark tools can be found on the Navigation Tab.



a. Save:

To create or save a bookmark for future reference, choose this option. The user will be shown a Bookmark Creation GUI to name and save the bookmark. Bookmarks are saved with an MPD (MARS Project Document).

Bookmark Cre	ation
Bookmark	sample_bookmark
	OK Cancel

b. Visit:

To visit a saved bookmark, use this option. A list of saved bookmarks will appear. Choose the desired bookmark and click 'OK' to view the bookmark placement.

Bee Bookma	rk Visit		
Bookn	narks		
samp	le_bookmark		
	OK		
	OK	Cancel	

c. Delete:

To delete a saved bookmark, use this option. A list of all saved bookmarks will appear - choose the bookmark to be deleted by highlighting it and clicking 'Delete' at the bottom of the window.

Bo	okmark De	lete				x
	Bookmarks					
	sample_boo	okmark				
			_			
		Delete	•	Can	cel	

6. Jump to:

MARS[®] provides three methods to quickly navigate to a specific area-of-interest, as described below:

a. XY Location:

The 'Jump to XY' button on the Navigation Tab allows the user to navigate to a specific X, Y coordinate.

Imp To XY	Location
Enter a loc	ation (X, Y) to put in the center of the view:
x	3135648.123
Y	1697907.479
	OK Cancel

b. Tile:

The 'Jump to Tile' button on the Navigation Tab allows the user to navigate to the extent of a specific tile by using a unique field value. To use this tool, a tile shapefile (*.shp) must be loaded into MARS[®].

BB Jump To Tile	
To view a specific	tile, select a field and enter a unique value for that field:
Field	TName
Value	
	OK Cancel

c. Check Point:

The '**Jump to Check Point**' button on the Navigation Tab allows the user to navigate to a specific check point location. To use this tool, a check points file (*.csv or *.shp) must be loaded into MARS[®].

Jump To Check Point
Select a check point to put in the center of the view:
Check Point MILE_HIGH
OK Cancel

7. Check Point Report:

When running a Check Point Report, the best performance can be obtained by using a computer with a discrete (and preferably, high-end) graphics card, especially when loading hundreds of GB or more of LAS data. Once the data is loaded, turn off the 'LAS' layer in the Table of Contents but leave all individual file entries in this layer checked on. Next, load the check points file (*.csv or *.shp) and then proceed with running the report.

8. Double-Click on Check Points in Report:

To use this shortcut, which may speed processes in QA/QC, a check points file (*.csv or *.shp) must be loaded into MARS[®] along with the corresponding LiDAR data. Once the required data is loaded, the user can zoom to specific check points by double-clicking on them in the check point report. To run a check point report, make sure both the LiDAR data September 4, 2024 Page 11

and corresponding check points file are loaded into MARS[®], then go to the QA/QC Tab and click the '**Check Point Report**' button. Choose the classes on which to run the check point report, the elevation calculation method, and the vertical units of the loaded LiDAR data. Click 'OK' and the report interface will appear. In the 'Statistics per Check Point (in data units)' section of the report, choose a check point and double-click on the check point ID; MARS[®] will zoom to that selected check point in the LAS Map View window.

9. Display Options:

The 'Display Options' interface (Options Tab, Display button) is meant for use with LiDAR data and the Color by Elevation tool (on the View Tab) and allows the user to choose custom display options which best fit their needs. This GUI may be used to prevent color skewing, which may occur when a small quantity of point values do not match values which are popular among the majority of points being displayed and increase the performance capabilities inside MARS[®]. The display options allow the user to apply histogram clipping and stretching, as well as standard deviation stretching so that the resulting display is the most correct. There are three (3) separate methods available to the user. If the user wishes to make any of the custom settings the new default settings, simply choose the 'Make Default' button and these custom settings will be saved and available to the user the next time the 'Display Options' window is opened, even in a new session of MARS[®].

- 1. **Minimum/ Maximum:** With this option, the user may specify a minimum and maximum color range stretch for a histogram.
- 2. **Standard Deviation:** With this option, the user may specify a number of sigmas to include in the display for both the left- and right-hand sides of a standard bell curve for a standard deviation stretch.
- 3. **Histogram:** With this option, the user may specify a percentage cut-off for both the left- and right-hand sides of a histogram clip.

Display Options	Bisplay Options	🔡 Display Options
Method to use	Method to use	Method to use
Minimum/Maximum	Minimum/Maximum	Minimum/Maximum
Standard Deviation	Standard Deviation	Standard Deviation
Histogram	Histogram	 Histogram
Min/Max	Min/Max-	Min/Max
Minimum 0	Minimum 0	Minimum 0
Maximum 5280	Maximum 5280	Maximum 5280
Standard Deviation	Standard Deviation	Standard Deviation
Number of sigma - left side 2	Number of sigma - left side 2	Number of sigma - left side 2
Number of sigma - right side 2	Number of sigma - right side 2	Number of sigma - right side 2
Histogram	Histogram	Histogram
Percentage cut off - left side 5	Percentage cut off - left side 5	Percentage cut off - left side 5
Percentage cut off - right side 5	Percentage cut off - right side 5	Percentage cut off - right side 5
Selected Vector Highlighting	Selected Vector Highlighting	Selected Vector Highlighting
Color Line Weight (Size) 2	Color Line Weight (Size) 2	Color Line Weight (Size) 2
Point Size 10	Point Size 10	Point Size 10
Background	Background	Background
Background Color	Background Color	Background Color
Remote Desktop	Remote Desktop	Remote Desktop
Resize window while drawing cross section	Resize window while drawing cross section	Resize window while drawing cross sec
Make Defaults	Make Defaults	Make Defaults

10. MARS[®] Task Manager:

The MARS® Task Manager button is located on the 'Tools Tab'.

The task manager will allow the user to monitor and/or end multiple MARS[®] processes at once. To end a process, highlight it and it will appear in the 'Process Name to End' text box. Click on the 'End Process' button to end the chosen process. Note, however, that the session (instance) of MARS[®] that is running the MARS[®] Task Manager cannot be ended this way. The 'Refresh' button allows the user to refresh the 'MARS[®] Task Manager' without closing and reopening the tool – ending a process will cause an automatic refresh.

Star MARS Task Manager	
Current MARS Processes MARS MARSPrep	Process Name to End MARSPrep End Proces
	Help
	Refresh

11. Undo/Redo Buttons for Hand Editing Use:

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These buttons (on the Edit/Filter Tab) allow the user to undo/redo manual edits made in the profiling window or the main window. Having this capability in MARS[®] can dramatically increase the efficiency and accuracy of hand filtering data.

12. Add Spatial Index:

This tool creates a spatial index on one or more LAS files to enable MARS[®] to read and display the point data. It can add spatial index information, remove it, or mark any existing spatial index records as superseded. Either of the last two uses may be necessary for using the files in other software.

<u>NOTE:</u> For best stability and faster performance, LAS files that have been spatially indexed in an older version (v2017.2 or earlier) should be re-indexed using version 2018.0 or later of MARS[®]. This can be done quickly in two

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steps using the multi-threaded 'Add Spatial Index' tool - the 'Fast Remove Index' option followed by the 'Add Spatial Index' option. See the paragraph immediately before the screen shot of the tool interface for more information. Also note that issues may occur with LAS files if they are spatially indexed in a newer version of MARS[®] and then have their index records removed in an older version.

There are two ways to use 'Add Spatial Index':

1) Add LAS files to MARS®

If LAS v1.4 data without the necessary spatial indexing is among the files selected to be loaded into MARS[®], the user will be provided a list of those files and three options for handling them:

Eist of LAS	Files Not Spatially Indexed	—		×
The following f	iles are not spatially indexed:			
D:\MARS\QC D:\MARS\QC D:\MARS\QC D:\MARS\QC D:\MARS\QC D:\MARS\QC	_Mod_test_data\DSD_fully_v1.4\01_Boresight _Mod_test_data\DSD_fully_v1.4\01_Boresight _Mod_test_data\DSD_fully_v1.4\01_Boresight _Mod_test_data\DSD_fully_v1.4\01_Boresight _Mod_test_data\DSD_fully_v1.4\01_Boresight _Mod_test_data\DSD_fully_v1.4\01_Boresight	_1.4_p6` _1.4_p6` _1.4_p6` _1.4_p6` _1.4_p6`	Unpreppe Unpreppe Unpreppe Unpreppe	ed\LDF ed\LDF ed\LDF ed\LDF ed\LDF ed\LDF
<				>
	Spatially Index LAS Files and Add Them to f	Project		
	Number of threads to use 1			
	No Change to LAS Files and Add Them to F	roject		
	Ignore (Will not Add Them into Project)		

a) Choosing 'Spatially Index LAS Files and Add Them to Project' will permanently prepare the data (by modifying the file header) for viewing. This process may be multi-threaded by entering a number greater than 1 in the 'Number of threads

to use' text box before clicking the 'Spatially Index...' button. *Please note* the explanatory text in the interface (see above) concerning multi-threading. For best performance, there should be a minimum of five (5) GB of RAM <u>available</u> (not just installed) per thread. Multi-threading the Spatial Indexing functions across a USB 2.0 connection is not recommended as the intensive file reads/writes (disk I/O) may cause hangs or slower overall performance than single-threading. USB 3.0 or later can be used but may be limited in performance depending on the access speed of the external drive.

A second window will appear with options for File Source / Point Source ID numbering.

III File Source/Point Source ID Numbering		×
Options		
\bigcirc Assign collection scan numbers to all files		
This option should be used to assign a unique sequential nur as the File Source ID (and the same number to each of the p the Point Source ID) if numbers have not been assigned prev also be used to assign new numbers if desired (overwriting ex caution below.	nberto each oints in the f riously. It ca tisting ones)	n file ile as an . See
Enter starting number greater than 0		
Retain existing collection scan numbering for all files		
This option should be used to prevent overwriting of existing numbers (File Source and Point Source IDs), as in the case v exports such as tiled data have already been produced from files. See caution below.	collection so where LAS the original s	:an swath
Caution		
If files have no existing File Source/Point Source ID numbering and assigned, certain viewing and QC options may not be available. Alt files with existing numbering are overwritten, the link between them previously produced LAS data that came from them will be lost. Thi that points cannot be traced back to their source files.	none is emately, if and any s means	
Неір ОК	Can	cel

Depending on the user's preference or requirements, the files can be sequentially renumbered (in the order listed in the original window) by choosing the 'Assign collection scan numbers to all files' radio button and entering a starting number, or they can be indexed with no changes to any collection scan numbering they already have by choosing the 'Retain existing collection scan numbering for all files' radio button. The 'Retain' option is the default. *Please read the method descriptions and caution statement before proceeding.*

If using the 'Assign' option, please note that LAS version 1.4 can have collection scan numbers of 1 to 65,535. Keep this limit and the total number of files in mind when entering a starting number.

IIII File Source/Point Source ID Numbering				
Options				
Assign collection scan numbers to all files Assign collection scan numbers Assign collection scan Assign collection Assign c				
This option should be used to assign a unique sequential number to each file as the File Source ID (and the same number to each of the points in the file as the Point Source ID) if numbers have not been assigned previously. It can also be used to assign new numbers if desired (overwriting existing ones). See caution below.				
Enter starting number greater than 0 25				
Retain existing collection scan numbering for all files				
This option should be used to prevent overwriting of existing collection scan numbers (File Source and Point Source IDs), as in the case where LAS exports such as tiled data have already been produced from the original swath files. See caution below.				
Caution If files have no existing File Source/Point Source ID numbering and none is assigned, certain viewing and QC options may not be available. Alternately, if files with existing numbering are overwritten, the link between them and any				
that points cannot be traced back to their source files.				
Help OK Cancel				

After the choice has been made, click 'OK' to start the indexing and a status bar window will pop up. During this time, all files will be tested for empty 'System Identifier' header fields, and if found, will have this field populated with 'OTHER' (see the LAS file specifications on the <u>ASPRS LAS File Format</u> <u>website</u>). Files with values already in place will not have this field altered. When complete, the files will be loaded.

b) Choosing 'No Change to LAS Files and Add Them to Project' will *temporarily* prepare the data for the current session of MARS[®]. When indexed in this manner, no changes are made to the file header and the data will need to be re-indexed (either permanently or temporarily) if it is later loaded into another MARS[®] session.

c) Choosing 'Ignore (Will not Add Them into Project)' will cancel the loading of any files without spatial indexing, but will load any previously indexed ones that were part of the original selection.

2) Using the 'Add Spatial Index' interface - This method will permanently modify the header of LAS files when spatial index information is added or removed.

To bring up the interface, go to the Project/Data Preparation tab and click the 'Add Spatial Index' button.

- ✓ Navigate to the files to be spatially indexed by clicking on the 'Add' button. Files may be removed from the list by highlighting them and clicking on the 'Remove Selected' or 'Remove All' buttons.
- ✓ Choose one of the <u>Collection scan options:</u>

- Incremental: Assigns sequential collection scan numbers to each LAS file in the list to be spatially indexed. Using this option will overwrite any existing collection scan numbering in the LAS files. Enter the desired starting number in the 'Starting collection scan number' text box, keeping in mind that LAS version 1.4 files are limited to collection scan numbers of 1 to 65,535. If multi-channel files are being processed, check the 'Group Multi-Channel LAS files (one number per group)' box to have the same collection scan number assigned to each file in the group. The tool requires that files in a multi-channel group be named identically starting with the letter 'L' except for a unique digit denoting the channel number following the mandatory letter 'C' for example, 'L1-1-140324_A-C1_r.las and 'L1-1-140324_A-C2_r.las' for this collection scan numbering method to work.
- No Assign Keep the collection scan number of every point: No changes are made to collection scan numbering that may exist in the LAS files. This is the default.
- Set all files to one collection scan number: Assigns only one collection scan number to all listed files. This option will overwrite any existing collection scan numbering in the LAS files. Enter the desired number in the 'Starting collection scan number' text box, keeping in mind that LAS version 1.4 files are limited to collection scan numbers of 1 to 65,535.
- ✓ <u>WKT</u>: This area shows any existing WKT-based coordinate reference system definition for the added files and allows the information to be edited. Changes made here will be applied only when <u>adding</u> spatial indexing.
- ✓ <u>Multi-Threading</u>: The 'Add Spatial Index' tool is capable of multi-threading the indexing process. To multi-thread (which may shorten the processing time), enter the desired number of threads up to the maximum available for the computer. For best performance, there should be a minimum of five (5) GB of RAM <u>available</u> (not just installed) per thread. Multi-threading the Spatial Indexing functions across a USB 2.0 connection is not recommended as the intensive file reads/writes (disk I/O) may cause hangs or slower overall performance than single-threading. USB 3.0 or later can be used but may be limited in performance depending on the speed (spin rate) of the external drive.
- ✓ <u>Class options</u>: This option allow a second spatial index to be created based on all classes EXCEPT the one(s) listed in the 'Majority Classes' box. Click the 'Select' button to choose the desired majority classes. When one or more of the chosen classes are turned off using the 'View Classification' button, performance is increased during display-related operations such as pan and zoom. In addition, a higher percentage of the available point cloud will be displayed for a given window extent. If more than one class was chosen as a majority class during indexing, the performance boost will be highest when all majority classes are turned off.
- ✓ <u>VLR/EVLR options</u>: The 'Remove all VLRs/EVLRs before spatial indexing' option (unchecked by default) can be used to completely remove <u>all</u> Variable Length and/or Extended Variable Length Records (not just indexing records) from the LAS files listed in the 'Files to spatial index' box during the 'Add Spatial Index' process. This function works only when adding indexing, not when using the 'Remove Spatial Index' or 'Fast Remove Index' buttons.

- ✓ Note: All files will be tested for empty 'System Identifier' header fields and, if found, will have this field populated with 'OTHER' (see the LAS file specifications on the <u>ASPRS LAS File Format website</u>). Files with values already in place will not have this field altered.
- ✓ Click 'Add Spatial Index' to index the data, or 'Remove Spatial Index' to delete any existing spatial index records. Removal will make LAS file sizes a little smaller, but will cause the files to be unloadable in future MARS sessions unless they are re-indexed. The 'Fast Remove Index' button will mark all indexing records as superseded (ignored) without actually deleting them. As with complete removal, this makes the files unreadable in future MARS sessions unless they are re-indexed, but the reindexing process will be much faster. Either of the removal options may be helpful in loading data into other lidar software. Neither the 'Remove Spatial Index' function nor the 'Fast Remove Index' function will make any changes to collection scan numbering.

🗱 MARS Spatial Index			×
Files to spatial index			
C:\MARS\Sample_Data\MARS_Sample_Lidar.las		Add	
	Remo	ve Selec	ted
	Re	move All	
	Count	1	
Collection scan options	1		
O Incremental Group Multi-Channel LAS files (one number per group)			
No Assign - Keep the collection scan number of every point			
O Set all files to one collection scan number			
Starting collection scan number 1			
WKT COMPD_CS["NAD83(HARN) / Colorado Central (ftUS) + NAVD88 height (ftUS)	- US Ge	Edit	
Multi-Threading Number of threads to use 1			
Class options			
Use optimized indexing when one or more majority classes (like ground) are r	not displa	yed	
Majority Classes 2/0 Ground (All) Select			
VLR/EVLR Options Remove all VLRs/EVLRs before spatial indexing			
Status			
0%		Clear	
Help Add Spatial Index Remove Spatial Index Fast Remov	e Index	Can	cel

13. Fast TIN:

The 'Fast TIN' option inside MARS[®] should be used when hand filtering. 'Fast TIN' will increase the speed at which TINned data can be rendered, especially during pan and zoom operations, and will make editing tasks go faster.

IMPORTANT NOTE: The 'Fast TIN' option should <u>never</u> be used when working with breaklines. Breaklines are purposely ignored (to enhance rendering performance) when the 'Fast TIN' option is used, and therefore will not have the desired visual effect on the ground surface.

To use this option, go to the Options Tab, click the 'Performance' button, and check the '**Fast TIN**' box. 'Fast TIN' can also be toggled on/off by using the shortcut key combination 'Ctrl-T.'

Performance Options	
Cache Options	
Cache points into available RAM	
Percent of available RAM used to cache points 75	%
TIN Options	
Нер ОК	Cancel

14. 'Reference Reclass – Closest Distance' Tool (available with Production license only):

This tool, found on the Tools Tab, allows the user to reclassify one set of LAS files (the 'Unclassified' input files) based on the classes found in another set of LAS files (the 'Classified' input files), by using various parameters found in the LAS files. The tool determines which points will be reclassed based on the LAS points' recorded <u>time and position</u>. This is a special version of the 'Reference Reclass' Tool: (1) Time will be used to determine possible candidate points, and (2) X, Y, Z will be used to determine the closest candidate point. This tool can process LAS data when the two inputs are in different time formats (for example: GPS Week Time and Adjusted GPS Time) because it also accounts for the position of an LAS point.

Classified: Browse to a folder which contains LAS files that have one or more classifications in each file.

These files are usually in a tile scheme form, but other files can be used.

Unclassified: Browse to a folder which contains one or more files that have all points classified as a single default value. These files are usually in collection scan form, but other files can be used.

- **Output:** Browse to an output folder to store the results of this LAS classification transfer. This selection choice is <u>optional</u>; if the user does not choose an Output folder, the 'Unclassified' input data is overwritten with the newly classified data based on this reference reclass function.
- *Tile Option:* Optionally, the data can be tiled upon completion based on a user-selected polygon shapefile tile scheme.
- *Class Requirement:* Checking this option will allow the tool to use every classification offered in the 'Classified' data to reclass points in the 'Unclassified' data. When unchecked, individual classes can be chosen to participate.

- **Source Fields That Must Match Reference:** This area of the interface gives the user the ability to use the values offered from the Classified to the Unclassified LAS files as a reference.
- **Cache Unclassified LAS:** Checking this option will cache all of the points specified in the 'Unclassified' input path to RAM per file. This will make the tool process more quickly than it would working from two separate locations (specified by the 'Classified' and 'Unclassified' input paths) on a network.
- *Virtual Tile Size:* The user may specify a virtual tile size here. The virtual tile size will identify the size of the area which the tool will process at any one time. Computers with more RAM can process larger areas resulting in a shorter time to completion.

BB LAS Reference F	Reclass - Closest Distance
Input/Ouput Fo	Iders
Classified	
Unclassified	
Outout	D:\Temp
Output	D:\MARS\dump
Tile Option	
🔽 Tile the o	utput
Tile Shapefil	e
File	C:\MARS\Sample_Data\MARS_Sample_Project_Tiles.shp
DB Field	TName 👻
Class Requirem	ent
📝 Map all cl	asses from reference files
-Source Fields T	hat Must Match Reference
👿 Time	X Position V Intensity Need Time Conversion
Z Position	Y Position V Return Cache Unclassified LAS
This is a special v	ersion of Reference Reclass: (1) GPS Time will be Virtual Tile Size
used to zoom into	certain point candidates, and (2) X, Y, Z will be 2000
Used as that the d	Rosest point will become the candidate.
Status	
	Keclassity

15. Save to Local Option (Temporary Folder): a. Export:

The 'Save to Local Option' can be found in the export interface for the following export types: Flightline Separation - JPEG 2000, both ENVI Grid types, Esri ASCII Grid, Float Grid, IMG Grid, LAS, LAS Grid, TIFF Grid, Hillshade - JPEG 2000, LiDAR Spatial Distribution Verification GRID - JPEG 2000, LiDAR Raster JPEG 2000 Grid, LiDAR Point Density – Float

Grid, and both PLS-CADD Code types. This tool speeds up MARS[®] by using temporary local disk space during export processing and is typically used when the 'Output Directory' is a network location. There is no benefit to using it when the output is local. To use this option during export of one of the file types listed above, check the **'Use temporary local disk space to speed up processing'** check box and designate a temporary folder found on one of the computer's local drives. The 'Temporary Folder' specified <u>WILL NOT</u> be the output folder used for the final export. The specified 'Temporary Folder' is simply a directory with free space which can be used to speed up the processing of raster-based exports.

Once the user has specified a temporary folder, MARS[®] will verify that there is enough space in the temporary folder to use in processing and the results will be shown in green below the 'Temporary Folder' browse box. If the 'Required Space' amount is less than the 'Free Space' amount shown, the computer will use the local folder for processing. <u>NOTE:</u> *Most versions of Windows restrict an application's output of files to the root directory of drives. It is strongly recommended that an actual folder be used for this option.*

🗱 MARS Export - Flightlin	e Separation - JPEG 2000		– 🗆 🗙
		Save Settings to File	Load Settings from File
Output Layout Filter	s Options Grid		
Output Direc	D:\TEMP Save to Local Option Use temporary local disk space to speed up processing Temporary Folder	Browse	Browse

b. Batch Process Tiles:

The 'Save to Local Option' may also be used in conjunction with the Batch Process Tiles tool. The option works the same way in this interface as it does in the export interface (see item **a**., above).

🗰 Batch	Process 1	Files				- 🗆	×
Output	Tiles	Script/Filters	Options				
)utout I A S	Ele Names					
, C	Field fo	r Tile Name	TName	~			
	T Iold Io						
		Prefix					
		Suffix					
	Output	Directory	M:\Convert_Ter	np			
- 5	Save to Loo	cal Option					
	⊡ Use	e temporary i	local disc space	to speed up processing			
	Temporary	y Directory	D:\Temp				
		Fre	e Space: 733,	957.1 MB			
	AS Option	S					
	Point D	ata Record	Format				
	Forma	t 6 (30 Bytes	- GPS)	\sim			
				Percentage Completed	Multi-Thread	ling	
				r crocinage completed	Number	of threads to u	8e
Elapsed	Time:		-		1		
Estimate	d Time to	Complete:	-				
Hel	p				Ru	in Ca	ancel

c. QC Module (available with Explorer QC or Production license):

The 'Save to Local Option' works the same for this module as it does for the previous two examples - it speeds up performance by using temporary local disk space during processing. It is available in all the drop-down tools within the QC Module, including the latest 'USGS NGP LBS – 2022 rev. A' compliance testing tool.

MARS QC - USGS 2022 rev. A					—		×
Input Collection Data Processing/Handling		Input Requirement Ma	atrix				
LAS Files					Save Settin	ngs to File	
Classified LAS Folder (final filtered tiled files)				Browse	Load Setting	s from File	•
Generated Swaths							
Keep generated swaths when complete				Browse			
NOTE: The extents of the tiled files in the Classified LAS F Shapefiles	older must match	n the extents of the tiles in	n the Tile Scheme.				
Tile Scheme	Browse	DB Field (Required)		~			
DPA Boundary	Browse	DB Field (Required)		~			
Exclusion Shapefile	Browse						
Misc Input Quality Level QL0 (5.0 cm RMSEz) QL1 (10.0 cm R	MSEz)) QL2 (10.0 cm RMSEz)) QL3 (20	0 cm RMSEz)			
Lidar Check Points file (see Help file)				Browse			
Horizontal Data Units Meter 🗸		Vertical Da	ata Units Meter	~			
Title Page							
Project Name							
Description					Elanged Time		
					Lapsed Time		
Corporate Logo				Browse	-		
Output					Estimated Time Fo	or Current S	tep
Output Folder				Browse			
Output PDF File Name QC 2022 All Save to Loc	al Option				Elapsed Time:		
	porary local disk	space to speed up proce	ssing		-		
Evisting Files	Folder			Browse	Estimated Time to	o Complete	
Overwrite O Skip Available S	pace:				-		
Multi-threading Current Step			Status	1			
Overall Progress				Help	Run		

16. Save/Load XML Settings:

a. Export:

Another way to improve performance in MARS[®] is to use the '**Save Settings to File**' and '**Load Settings from File**' options found in the 'Export' interface. The ability to save export settings will allow the user to make several separate exports with the same settings much more quickly than entering the setting specifications separately for every export and eliminates the possibility of typos. To use this tool, simply open the Export or Export Area interface and enter the parameters for export. Click on the 'Save Settings to File' button, navigate to the location in which the settings will be saved, name the XML file, and choose 'Save'. Now that the settings have been saved, the user may exit MARS[®] and September 4, 2024 Page 22

when another MARS[®] session is started, the 'Load Settings from File' option will allow the user to navigate to the folder which contains the previously saved XML file and load it into the MARS[®] export application.

b. QC Module (available with Explorer QC or Production license):

The '**Save Settings to File**' and '**Load Settings from File**' options are available in all the drop-down tools of the 'QC Module'. When using a previous settings file with 'Load Settings from File,' the file is checked for compatibility with the drop-down tool being used. Otherwise, these two buttons function in the same way as for 'Export' (above).

c. GeoCalc:

The **'Save Settings to File'** and **'Load Settings from File'** options are also found in the 'GeoCalc' interface. They function in the same way as for 'Export' (above).

d. Batch Process Tiles:

The user can create or edit multiple macro filters using the 'Create/Edit Script' tool. To use this tool, go to the Edit/Filter Tab and click the 'Create/Edit Script' button. The ability to save the specifications inside this interface allows the user to perform a particular macro filter or auto filter multiple times without having to enter the settings for the filter into the interface each time. The 'Save as' option, found inside the 'Create/Edit Script' interface, functions very similarly to the 'Save Settings to File' tool inside the export dialog. Simply enter parameters for the batch script by adding, editing, or deleting filters and/or extraction tools within the macro. When all entries are complete, click the '**Save as'** button. Navigate to the location in which the settings will be saved, name the XML file, and choose 'Save'. Now that the settings have been saved, the user may exit MARS[®] and when another MARS[®] session is started, the user may choose the 'Browse' button located to the right of the '**Existing Batch Script File**' browse box and navigate to the folder which contains the previously saved XML file and load it into the MARS[®] with the '**Load Script'** option. To use this option, go to the Edit/Filter Tab and click the 'Load Script' button. Browse to the folder which contains the desired XML file, choose it, and click 'Open' to load it into MARS[®]. Once a batch script is loaded using this tool, it can also be edited. Upon loading the batch script, it will become an option in the Filter Action drop-down box. Use the drop-down arrow to choose the desired macro if more than one exists within the batch script.

e. 'Breakline Properties' Window:

This tool is for use with breaklines. Any breaklines which can be loaded into MARS[®] (or are created in MARS[®]) can be edited to fit the user's needs. With this interface, the user can change the color and description of any breakline type, determine which features will be displayed, insert new features, rename features, and even load an already existing XML template with custom features, colors, and codes. In the Compilation Options section of the interface, the user can search for points to use in elevation calculations, delete certain breakline classifications, and change the distance between points in a segment of a breakline, among other options.

Breakline Properties											—		×
Up Down Remove													
All Breaklines	Feature Name	Code	Geometry Type		Z Mode		Color	Style	Weight	Snap Mode		Tolerance	TIN
Boad Centerline	LiDAR Delete	3	Polygon	\sim	TIN	\sim		0	0	Vertex	~	2	\checkmark
Road Edge	Road Centerline	6	LineString	\sim	MedOnVertex	\sim		0	0	Vertex	\sim	2	\checkmark
Stream	Road Edge	11	LineString	\sim	MinOnVertex	\sim		0	0	Vertex	\sim	2	\checkmark
- River	Stream	24	LineString	\sim	MinDecreasing	\sim		0	0	Vertex	\sim	2	\checkmark
Breakline	Pond	25	Polygon	\sim	MinLock	\sim		0	0	Vertex	\sim	2	\checkmark
Trans Attach	River	26	LineString	\sim	MinDecreasing	\sim		0	2	Vertex	\sim	2	\checkmark
	Breakline	62	LineString	\sim	MaxOnVertex	\sim		0	0	Vertex	\sim	2	\checkmark
	Trans Attach	63	Point	\sim	TIN	\sim		0	0	Vertex	\sim	2	\checkmark
	Static Attach	64	Point	\sim	TIN	\sim		0	0	Vertex	~	2	\checkmark
Insert New Feature		Compilation Option	8								_		
		(The distance from a new breakline point to search Search Radius 5 for LIDAR points to use in elevation calculations)							ı				
Feature Name	Add Feature	Graund Chapitications 2/0 Graund (All)											
Update Feature Name		Ground Classifications 2/U Ground (All)											
	Update	Reclassed Points 20 - Superseded (Breakline)											
Feature name is the key to link the two views above the feature name via "Update" button (select an item	. You can only change in tree view first).	Reclass Buffer Width 5 (Distance to the side of a breakline to reclassify LAS points to the superseded classification.)								Reset to D	efault		
TIN Options	Grid Options								Make De	fault			
Fast TIN	Grid Cell Size 10 Number of passes of grid smoothing 3							OK					
		Locked Eleva	tion Change									UK	
Help Save Settings to File	Large Inc	rement -0.8		Small Inc	rem	ent -0.2					Cance	el	

17. 'Auto Calculate Virtual Tile Size' Grid Export Option:

Virtual tiles are used by MARS[®] to allow processing of manageable data sizes in RAM. A computer with less RAM needs smaller virtual tile sizes to complete an export while a computer with more RAM can process faster by using larger virtual tile sizes. An optional 'Auto Calculate Virtual Tile Size' checkbox is available on the 'Grid' tab of Export to optimize internal processing based on a combination of average point density, available RAM, and the number of threads to be used during the export.

//ARS Export - Grid - Float Grid	
	Save Settings to File Load Settings from Fi
Output Layout Filters Options Grid	
Grid Options Common Cell Size 3 Grid Smoothing Count 0 NODATA Value -9999	Auto Calculate Virtual Tile Size Virtual Tile Size 500
Grid Type Intensity Stretch ● Elevation ✓ Stretch intensity on entire exported	dataset Standard Deviation (2x) \checkmark
Color by Collection Scan Separation Colors Options Create Z Dif	ff TIFF file used to calculate RMSDz
TIN O Grid TIN method is the most accurate but may Grid method may produce false excess-set	rtake substantially longer. eparation values.
C LiDAR Spatial Distribution Density Verification	
Options for Density Verification	
Number of points required in cell 1 Minimum Zero C	Count to set NODATA value
Exclusion Shapefile	Browse
◯ Color By for LiDAR Raster	View Appearance Color Cycle
Data Type Eloat 32 Int 32 Unsigned 16 Unsigned 8 Shift L or	Coordinate Shift
Closest Point to Cell Centroid Grid from TIN O Min Point of	Cell O Max Point of Cell O Median Point of Cell
Fill Gap No Fill O Fast Fill O TINned Surface Fill (clean across Maximum distance to fill	s tiles) Internal Buffer Size for TINned Surface Fill
Input Data Type (Auto boundary algorithm)	Tile
0%	Multi-Threading
Elapsed Time: -	Number of threads to use 16
Estimated Time to Complete: -	
Help Only Displayed Files Will Be	Exported Export Cancel

18. Fast, Compressed JPEG 2000 Raster Exports: a. Flightline Separation:

This tool functions similarly to the 'Color by Z Delta' tool and creates a JPEG 2000 as the output product. Having a fast, compressed raster export type such as JPEG 2000 can increase display speed and productivity. This export type is intended for use over an entire project area. The *.jp2 that is generated is based on the relative height differences between LiDAR data in overlapping areas. The overlap area differences are color coded, allowing the user to immediately detect relative vertical accuracy problems. The non-overlapping areas will show Intensity gridded data for reference purposes only. This tool is useful for rapidly assessing the consistency of the LiDAR dataset's height and is highly useful in boresighting. Over hard surfaces (such as roads) the user can expect the vertical height within the same 'cell' to be the same regardless of the LiDAR collection scan from which the data originates. Differences are an indicator of a potential

mission anomaly (typically a GPS/IMU problem) or a post-processing data adjustment issue. In areas such as forests or fields, where vegetation growth varies according to the time of year, understandable error may be seen. Lastly, the overlaid collection scan separation coloration will have a transparency set to it so that the output raster will still have some feature definition visibility. Multi-threading capability is enabled for this export type which can increase the performance. Ideally, there should be a minimum of five (5) GB of RAM available (not just installed) per thread for best performance.

Example: The raster shown below was created by exporting to a JPEG 2000. Collection scan overlap is represented by the colored sections of the raster. The colors are rendered based on collection scan separation using the 'Color Options' button on the 'Grid' tab. There is a cross scan included in this example which runs horizontally rather than vertically. The areas with no overlap are rendered by intensity value (gray-scale) only.



b. Hillshade:

This tool allows the user to create a hillshade image or raster from gridded elevation float grids (*.flt). It is important to understand that the output file created by this tool is a raster. It is designed to display quickly, and will only work in 2D (orthographic) view, not in 3D. An image file, such as the JPEG 2000 produced by this export type, is much faster to display when using the pan, zoom in, or zoom out features than a float grid file would be. For a temporary hillshade rendered from a float grid(s), click on the 'Color by Hillshade' The button. However, display is much faster when the hillshade is exported as a JPEG 2000.

Below is a sample of an exported 'MARS_Sample_Data_Hillshade' JPEG 2000 file. Because the resulting file is a raster, panning and zooming is much quicker than when using float grids with the hillshade created 'on the fly.'



c. LiDAR Spatial Distribution Verification GRID Tool:

This tool is used to create a grid with values representing the presence (value=1) or void (value=0) of a first (of any) return LiDAR point within any portion of a predefined grid cell size. This tool creates a JPEG 2000 file as the final product. Having a fast, compressed raster export type such as a JPEG 2000 can increase display speed and productivity. The development criteria for this tool were based upon the USGS LiDAR Base Specification 2021 rev. A (June 2021 and subsequent revisions), as stated:

'The spatial distribution of geometrically usable points will be uniform and regular. Collections will be planned and executed to produce an aggregate first return point data that approaches a uniform, regular lattice of points. The regularity of the point pattern and density throughout the dataset is important and will be assessed by using the following method:

- Assess only nonwithheld, first return points of a single File Source ID.
- Exclude acceptable data voids previously identified in this specification.
- Generate a density raster from the data with a cell size equal to twice the design ANPS.
- Populate the raster using a count of points within each cell.
- Ensure that at least 90 percent of the cells in the grid contain at least one lidar point.

The USGS–NGP may allow lower passing thresholds for this requirement in areas of substantial relief where maintaining a regular and uniform point distribution is impractical.'

Below is an example result of the 'LiDAR Spatial Distribution Verification GRID' tool. The green areas represent cells with a value of '1', meaning they have at least one LiDAR point within the cell. The red areas represent cells with a value of '0', meaning they DO NOT contain any LiDAR points. In the example below it is easy to see that there is a body of water or other data void running through this area, which is the cause of the red cells with a '0' value. If the user were to implement the 'Minimum Zero Count' option when running this tool, the areas of contiguous '0' cells (the water body) would return a null value instead of a '0' value.



The 'LiDAR Spatial Distribution Verification GRID' tool will also output a results text file (*.txt) every time the tool is used. This file will be output to the same location as the JPEG 2000 (the location specified by the user in the output directory browse box). The text file will be named beginning with the date, time, and

'...LiDAR_Spatial_Distribution_Verification_Results.txt'. This allows each *.txt created to be unique. For instance, the file seen in the screen shot below was produced on February 2, 2011, at 2:45 pm.

🖺 20110202_144535_LiDAR_Spatial_Distribution_Verification_Results.txt

The text file will contain the following information: the number of cells with a '0' value, the number of cells with a '1' value, and the number of value = '1' cells as a percentage of the total number of cells. This last value will be the percentage of passing cells. This percentage needs to be 90% or above to comply with the USGS specifications mentioned above. The screen shot below shows an example of the information contained in the text file.

20140717_155500_LiDAR_Spatial_Distribution_Verification_Results.txt - Notepad	23
File Edit Format View Help	
Number of cells with value 0: 14885 Number of cells with value 1: 693338 Percentage of value 1 cells of total of 0's and 1's: 97.90%	*

d. LiDAR Raster JPEG 2000 export:

This tool is used to create a fast-exporting and fast-rendering JPEG 2000 raster from the loaded LiDAR data. The raster cells can be colored by Class, Intensity, Elevation, or RGB values (if present).

MARS® Technical Support – General Information

- Technical Support Hours: Weekdays from 9:00 AM 5:30 PM (U.S. Mountain Time Zone)
- Toll-free Telephone: (800) 544-1714
- E-mail: <u>MARSsupport@merrick.com</u>

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 ✓ Mark A. Stucky - MARS[®] Technical Support Specialist (United States/Canada) Office: (303) 353-3933

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Social Media



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